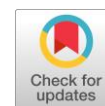


# Performance evaluation and mathematical analysis of direct sequence and frequency hopping spread spectrum systems under wideband interference



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## ABSTRACT

This paper presents performance evaluation and comparison analysis of Direct Sequence Spread Spectrum (DSSS) and Frequency Hopping Spread Spectrum (FHSS) systems. The evaluation and analysis are done based on the systems performance against wideband interferences. The interferences are signals with similar spectrum characteristic to the transmitted signals of DSSS and FHSS systems. Bit Error Ratio (BER) is used as evaluation parameter to assess the performance of both systems. Simulation and mathematical analysis are performed to test and verify the performance of both systems. Mathematical analysis also verifies that increasing Spreading Frequency on certain conditions will reduce the BER. This research also points out that FHSS system has a better performance compared to DSSS system indicated by smaller BER.



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## 1. Introduction

Spread Spectrum Multiple Access (SSMA) is one of the Multiple Access techniques in communication systems, that works by expanding the transmitted signal bandwidth to be larger than the bandwidth of the data signal [1]. Previous works discussing theory [2], techniques [3], and the developments of Spread Spectrum system [4] have been published since three decades ago. Spread Spectrum was originally applied to military communication system [5]. Currently, Spread Spectrum techniques have been widely used in many communication systems [6] such as GLOBALSTAR satellite communications system [5], Low Earth Orbiting (LEO) satellite communications network systems [7], GPS for satellite navigation system [8], Wireless Local Area Networks (WLAN) IEEE 802.11 system [8], optical codes for Fiber-optic Local Area Networks (LAN) [9], digital cellular radio system IS-95 for mobile voice communication [8], Wideband-CDMA for third-generation mobile communication system [8], wireless communication and control systems in Unmanned Aerial Vehicles (UAV) [10], underwater acoustic communication system [11]. This spread spectrum system is now developed for multiple access techniques on fifth generation (5G) cellular telecommunication system [12]. Spread Spectrum systems have been used in many other applications such as digital watermarking for copyright protection of audio, image and video, and multimedia data [13]-[15], digital watermarking for telemedicine [16], DC / DC converter circuit [17], LLC Resonant [18], and 3rd Generation Attachment Series (SATA-III) for reducing electromagnetic interference (EMI) problems [19].

Spread Spectrum systems have been used in various fields due to their characteristics that can solve interference problems. Characteristics of the Spread Spectrum systems offering advantages for communication systems have been described in [20]. Simulation study by using Matlab software as a digital signal processing tool has been done in [21]. The advantages of the Spread Spectrum systems compared to the FDMA and TDMA systems have been discussed in [22]. In general, there are two methods of Spread Spectrum, namely: Direct Sequence Spread Spectrum (DSSS) and Frequency Hopping Spread Spectrum (FHSS). Several works addressing a thorough study of those two systems have been done in [23-30]. In [23] and [24], design and simulation of both systems have been done on Matlab platform. In [25], a comparison study was done by changing the used signal bandwidth. Performance analysis by varying the pseudo noise (PN) sequence and modulation technique has been conducted in [26]. In [27], comparative analysis based on the resulting modulated signal form has been presented. In [28], both systems are analyzed for their ability to avoid interference based on the maximum number of users for the same receiver. McCune [29] and Shayesteh [30] studied the performance of Spread Spectrum systems against interference with narrowband frequency.

This research aims to simulate and analyse DSSS and FHSS performances when both systems are subject to wideband interference. The comparison analysis will be done based on the robustness of both systems against this type of interference. The used interference signal has similar spectrum behaviour to the transmitted signals of DSSS and FHSS systems. In other words, the generated interference signal employs similar frequency channel to DSSS and FHSS systems. BER parameter is used to determine the ability of each system to recover the data signal. This performance evaluation and mathematical analysis are important in the development of new multiple-access techniques, which are more resistant to wideband interference.

This paper is structured as follows; Section 1 introduces the principle, the applications, and the previous works on Spread Spectrum system. Section 2 describes an overview of Spread Spectrum System covering the signal processing techniques on DSSS and FHSS systems, and presents the methodology covering the design procedure for simulation. Section 3 describes the simulation results and mathematical analysis, then followed by remarks. Section 4 concludes the paper.

## 2. Method

### 2.1. Overview

Spread Spectrum is one of the multiple-access techniques that operates by expanding the transmitted signal bandwidth to be larger than the data signal [1]. Spread Spectrum systems are generally divided into two techniques: DSSS and FHSS. DSSS transmits signals at a single frequency but on very wide bands, while FHSS transmits signals with narrow bands, but quickly jumps from one frequency to the next. Fig. 1 illustrates the difference between the spectrum of DSSS and FHSS.

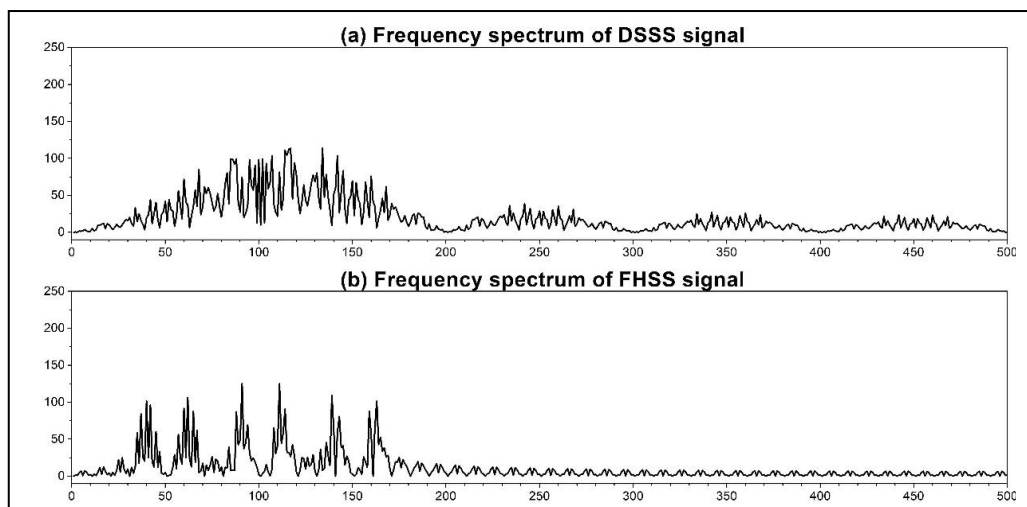


Fig. 1. Frequency spectrum of (a) DSSS & (b) FHSS

### 2.1.1. Direct Sequence Spread Spectrum

DSSS is most widely used type of Spread Spectrum, due to it is easier to implement and also has a high data rate. DSSS is a method to transmit data where the sending and receiving systems are on a wide frequency band. This wide channel allows the device to transmit more information at a higher data rate. Fig. 2 shows the signal processing steps on both transmitter and receiver of DSSS system. DSSS works by modulating the data signal with the carrier signal, then spreading it with a spreading signal (pseudo-random signal) whose frequency is greater than the frequency of the data signal (bitrate). In the receiver, the despreading signal is generated from multiplication by the carrier signal and the same spreading signal on the transmitter, reversing the encoding process on the transmitter [3]. The last process on the receiver is filtering to eliminate other signals, while keeping data signal.

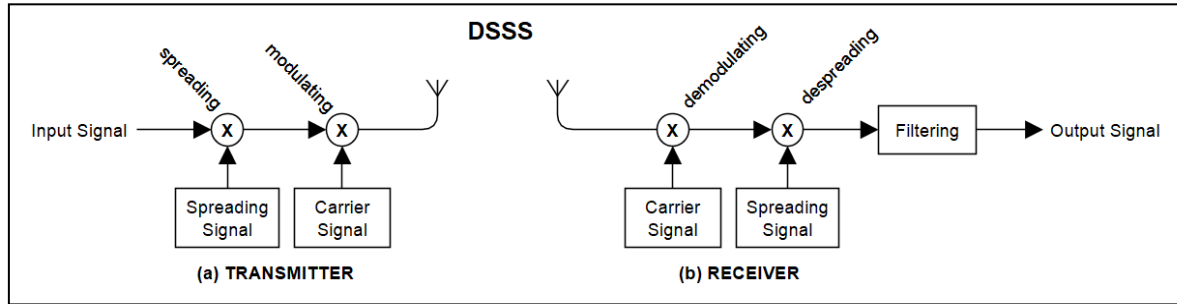


Fig. 2. Block diagram of the (a) transmitter and (b) receiver of the DSSS system

The mathematical model of the transmitted signal from the transmitter of DSSS has the following equation [1]:

$$T_D(t) = d(t)p(t)c(t) \quad (1)$$

where  $T_D(t)$  is transmitted signal of DSSS system,  $d(t)$  is data signal,  $p(t)$  is function of the spreading signal, and  $c(t)$  is function of the carrier signal.

The signals  $d(t)$ ,  $p(t)$ , and  $c(t)$  are formulated respectively as follow:

$$d(t) = \sum_{i=-\infty}^{\infty} d_i \psi(t - iT_d) \quad (2)$$

$$p(t) = \sum_{i=-\infty}^{\infty} p_i \psi(t - iT_s) \quad (3)$$

$$c(t) = A \cos(2\pi f_s t + \theta) \quad (4)$$

where  $d_i$  is data series,  $T_d$  is data signal period,  $p_i$  is pseudo noise series,  $T_s$  is spreading signal period,  $A$  is carrier signal amplitude,  $\theta$  is carrier signal phase,  $f_s$  is spreading signal frequency, and  $\psi(t - iT)$  is the delayed impulse unit function.

The delayed impulse unit function  $\psi(t - iT)$  is simply given by

$$\psi(t - iT) = \begin{cases} 1, & 0 \leq (t - iT) < T \\ 0, & \text{otherwise} \end{cases} \quad (5)$$

### 2.1.2. Frequency Hopping Spread Spectrum

In FHSS, the frequency of the spreading signal will continue to change or hopping at predetermined time intervals [27]. The transmitter selects the frequency to be used based on the spreading frequency series. Fig. 3 shows the block diagram of transmitter and receiver of FHSS system. From Fig.3, we can notice the main difference between DSSS and FHSS system. In FHSS system, the data signal is firstly modulated with the carrier signal, then spreading it with spreading signal whose frequency is constantly

changing. The frequency of a spreading signal is selected from a predetermined range of frequencies, and it is known only to the system users. Therefore, the communication process is difficult to disturb if the used frequency of spreading signal is unknown [3].

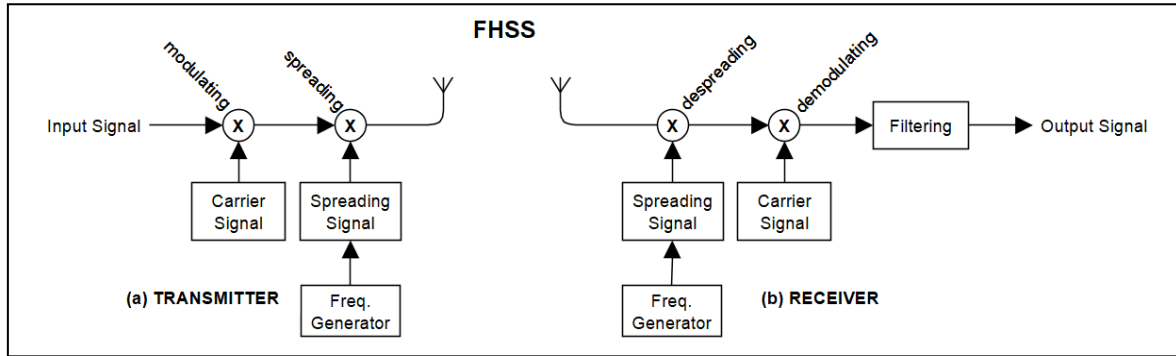


Fig. 3. Block diagram of the (a) transmitter and (b) receiver of the FHSS system

The mathematical equation of the transmitted signal of FHSS is given by [1]:

$$T_H(t) = d(t)c(t)p(t) \quad (6)$$

where  $T_H(t)$  is transmitted signal of FHSS system,  $d(t)$  is data signal,  $p(t)$  is function of the spreading signal, and  $c(t)$  is function of the carrier signal.

The data signal  $d(t)$  is like DSSS's data signal, while carrier signal  $c(t)$  and spreading signal  $p(t)$  are different as they are formulated by

$$c(t) = A \cos(2\pi f_d t + \theta) \quad (7)$$

$$p(t) = A \cos(2\pi t \cdot h(t) + \theta) \quad (8)$$

where  $f_d$  is data signal frequency,  $h(t)$  is hopping frequency given by:

$$h(t) = \sum_{i=-\infty}^{\infty} h_i \psi(t - iT_d) \quad (9)$$

Hopping frequency  $h(t)$  is a function of  $h_i$ , in which  $h_i$  refers to spreading frequency series.

## 2.2. Design Procedure for Simulation

There are two main contributions in this research works i.e.; (1) Simulation and (2) Mathematical analysis. Simulation is performed to simulate the process of sending and receiving signals for both DSSS and FHSS, while Mathematical analysis is done to verify that generated signal at each process is matched with the given mathematical model. The mathematical analysis is also used to justify the performance of both systems when wideband interference is added.

In the simulation, two main signals are generated. The first signal is data signal and the second signal is interference. Simulation procedure for comparing DSSS and FHSS is shown in Fig. 4, and it is called as Comparison program. Comparison program consists of single program that is used to generate Bit-error rate (BER) data for each system, in which the program is run 5000 times to get an accurate average of BER data. The output of this program is BER data for every variation of spreading frequency.

BER is defined as the number of high-value digital bits in transmission networks interpreted as low, or otherwise, then divided by the number of bit received or processed over several predefined periods.

$$BER = \frac{\#Bit \ errors}{\#Total \ bits} \quad (10)$$

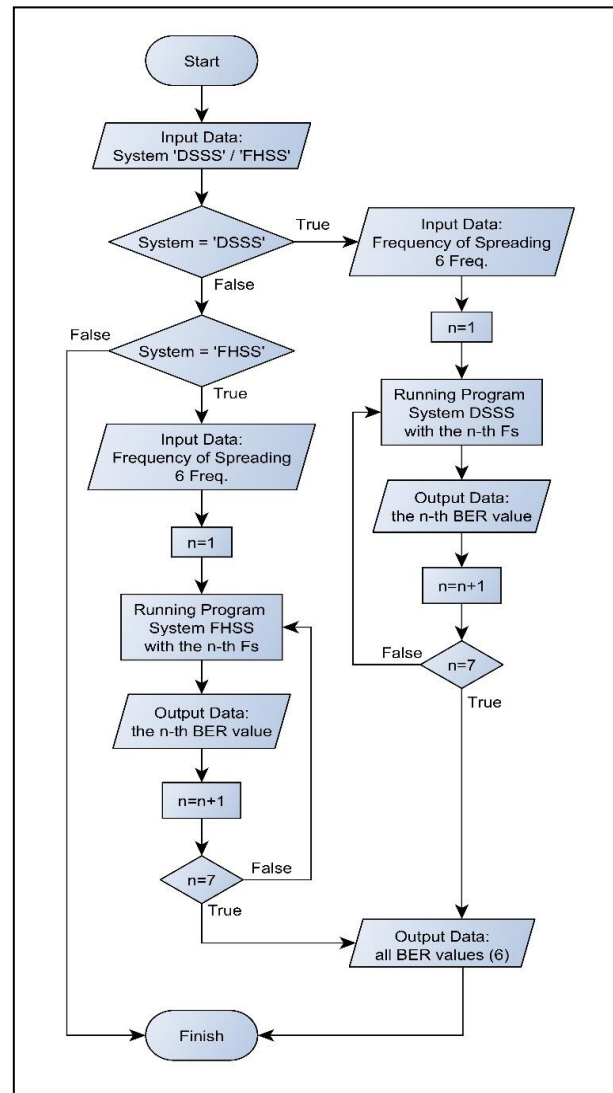


Fig. 4. Comparison Program flow chart

### 3. Results and Discussion

Simulation results comparing the performance of DSSS and FHSS are obtained by running the Comparison Program shown in Fig. 4. By keeping the bitrate at 10 Hz and varying the spreading frequency, the generated BER for each system will be recorded.

#### 3.1. DSSS System

Table 1 shows the simulation results of DSSS system when the bitrate is kept at 10 Hz, while spreading frequency is varied from 40 Hz to 250 Hz.

Table 1. BER of DSSS system

No	Spreading Frequency (Hz)	BER (%)
1	40	5.192
2	50	3.872
3	100	1.262
4	125	0.890
5	200	0.408
6	250	0.314

Table 1 indicates that there is a change in BER when spreading frequency is varied. When the spreading frequency is increased, the BER value tends to decrease. This behaviour can be explained from the mathematical analysis below. As mentioned before, there are two signals  $T_D(t)$  and  $T_I(t)$  generated from Transmitter 1 and 2 respectively.  $T_D(t)$  is transmitted signal without interference, while  $T_I(t)$  is interference signal. Fig. 5 demonstrates signal processing steps at the receiver for spreading frequency 40 Hz, while Fig. 6 shows the spectrum of the transmitted signal  $T_D(t)$  at 3 different spreading frequencies, i.e. 40 Hz, 100 Hz, and 200 Hz.

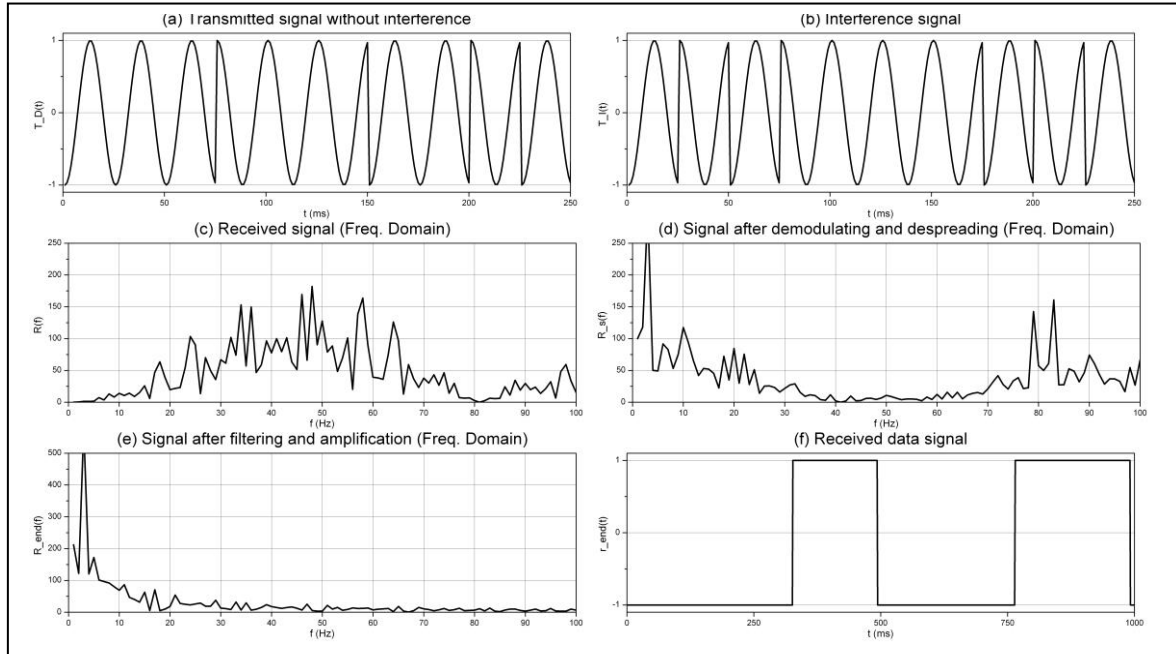


Fig. 5. Signal processing at receiver for DSSS system with spreading frequency 40 Hz

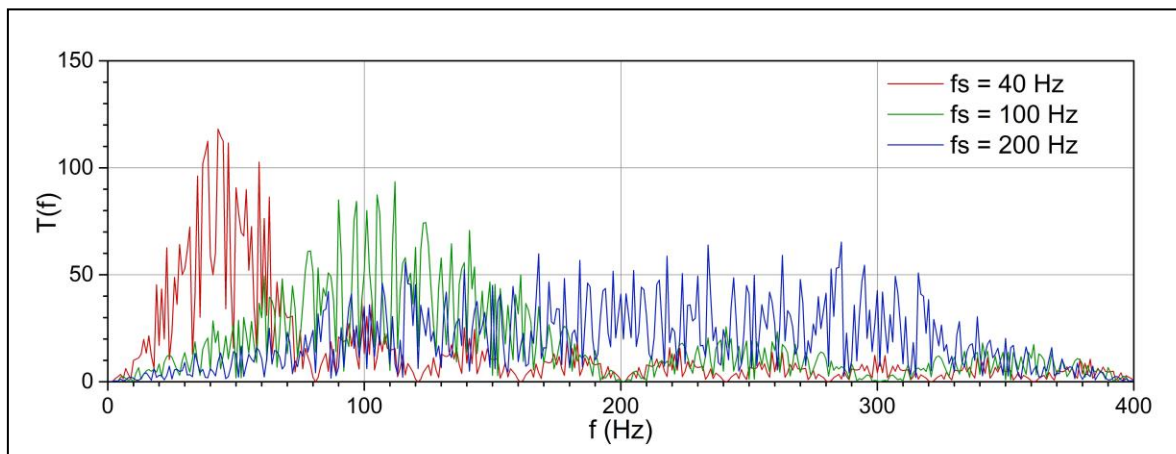


Fig. 6. Spectrum of transmitted signal of DSSS at different spreading frequency

Let  $T_D(t)$  is as shown in (1), while  $T_I(t)$  is given by:

$$T_I(t) = d'(t)p'(t)c(t) \quad (11)$$

where  $c(t)$  is carrier signal shown in (4),  $d'(t)$  and  $p'(t)$  are interference data signal and interference spreading signal shown as

$$d'(t) = \sum_{i=-\infty}^{\infty} d_i' \psi(t - iT_d) \quad (12)$$

$$p'(t) = \sum_{i=-\infty}^{\infty} p_i' \psi(t - iT_s) \quad (13)$$



The interfered data signal of DSSS system is given by:

$$r(t) = T_D(t) + T_I(t) = d(t)p(t)c(t) + d'(t)p'(t)c(t) \quad (14)$$

The interfered data signal  $r(t)$  becomes the received signal at the receiver. Then, the received signal passes through demodulation and de-spreading processes in order to obtain signal  $r_s(t)$  as follows:

$$r_s(t) = \left[ \frac{A^2}{2} d(t) \cos(2\pi 2f_s t) \right] + \left[ \frac{A^2}{2} d'(t)p'(t)p(t) \cos(2\pi 2f_s t) \right] + \left[ \frac{A^2}{2} d(t) \right] + \left[ \frac{A^2}{2} d'(t)p'(t)p(t) \right] \quad (15)$$

The signal  $r_s(t)$  after demodulation and despreading processes will be filtered by using FFT low-pass filter  $F(f)$  shown in (16). To recover data signal  $d(t)$ , the filter bandwidth of  $F(f)$  is set to  $f_F = f_d$ .

$$F(f) = \mu(f) - \mu(f - f_F) \quad (16)$$

$$\mu(t) = \begin{cases} 1, & t > 0 \\ 0, & t < 0 \end{cases}$$

The filtered signal in frequency domain is obtained from:

$$R_F(f) = R_S(f) \times F(f) \quad (17)$$

where  $R_S(f)$  is  $r_s(t)$  in frequency domain, and  $F(f)$  is filter function.

Thus, signal components having frequency greater than data frequency  $f > f_d$  or having period smaller than data period  $T < T_d$ , will be eliminated by the filter.

$$r_s(t) = \left[ \frac{A^2}{2} \left( \sum_{i=-\infty}^{\infty} d_i \psi(t - iT_d) \right) \cos(2\pi 2f_s t) \right] + \left[ \frac{A^2}{2} \left( \sum_{i=-\infty}^{\infty} d'_i \psi(t - iT_d) \right) \left( \sum_{i=-\infty}^{\infty} p'_i \psi(t - iT_s) \right) \left( \sum_{i=-\infty}^{\infty} p_i \psi(t - iT_s) \right) \cos(2\pi 2f_s t) \right] + \left[ \frac{A^2}{2} \left( \sum_{i=-\infty}^{\infty} d'_i \psi(t - iT_d) \right) \left( \sum_{i=-\infty}^{\infty} p'_i \psi(t - iT_s) \right) \left( \sum_{i=-\infty}^{\infty} p_i \psi(t - iT_s) \right) \right] + \left[ \frac{A^2}{2} \left( \sum_{i=-\infty}^{\infty} d_i \psi(t - iT_d) \right) \right] \quad (18)$$

Given the conditions that  $p_i \neq p'_i$  and  $f_s > f_d$ , the obtained filtered signal  $r_F(t)$  is

$$r_F(t) \approx \left[ \frac{A^2}{2} \left( \sum_{i=-\infty}^{\infty} d_i \psi(t - iT_d) \right) \right] \approx \frac{A^2}{2} d(t) \quad (19)$$

The filtered signal  $r_F(t)$  with  $A = 1$  will be amplified with gain 2 to obtain signal function that is similar to the data signal  $d(t)$

$$r_{end}(t) \approx 2r_F(t) \approx d(t) \quad (20)$$

However, there may be other signal components that can pass through the filtering process, if the following conditions occur:

1. If  $f_s = f_d$  and  $p_i \neq p'_i$ , then signal components that can pass through the filtering process:

$$r_F(t) \approx \left[ \frac{A^2}{2} d(t) \right] + \left[ \frac{A^2}{2} d'(t)p'(t)p(t) \right] \quad (21)$$

2. If  $f_s = 0.5f_d$  and  $p_i \neq p'_i$ , the filtered signal  $r_F(t)$  is

$$r_F(t) \approx \left[ \frac{A^2}{2} d(t) \right] + \left[ \frac{A^2}{2} d(t) \cos(2\pi 2f_s t) \right] + \left[ \frac{A^2}{2} d'(t) p'(t) p(t) \right] + \left[ \frac{A^2}{2} d'(t) p'(t) p(t) \cos(2\pi 2f_s t) \right] \quad (22)$$

3. If  $f_s > f_d$  and  $p_i' = p_i$ , the filtered signal  $r_F(t)$  is

$$r_F(t) \approx \left[ \frac{A^2}{2} d(t) \right] + \left[ \frac{A^2}{2} d'(t) \right] \quad (23)$$

From the mathematical analysis above, it can be noted that the required conditions for DSSS system to be robust against wideband interference  $T_I(t)$  are: 1)  $f_s > f_d$ , and 2)  $p_i' \neq p_i$ .

The larger spreading frequency  $f_s$  compared to bitrate  $f_d$  will have better robustness due to signal components other than  $\frac{A^2}{2} d(t)$  will have small chance to pass the filtering process. This mathematical analysis matches with the simulation results shown in Table 1, where the greater the spreading frequency  $f_s$  to be larger than the bitrate  $f_d$ , then the smaller BER of the system to be obtained.

### 3.2. FHSS System

In the simulation of FHSS system, 6 variations of spreading frequency are simulated. The bitrate is kept at 10 Hz. The largest spreading frequency used in FHSS is equal to the highest spreading frequency used in the DSSS system. Table 2 is the BER results for simulated FHSS system.

Table 2. BER of FHSS system

No	Spreading Frequency (Hz)	BER (%)
1	20 and 40	3.774
2	20 and 50	0.126
3	20 and 100	0.066
4	20 and 125	0.066
5	20 and 200	0.064
6	20 and 250	0.044

There are two hopping frequencies where one of them is kept at 20 Hz, while the other one is increasingly varied to 250 Hz. From Table 2, there is also a change in BER when hopping frequency is increased. When hopping frequency is increased, the BER value becomes smaller. We can also notice that BER of FHSS system is smaller than BER of DSSS system. Fig. 7 shows the signal processing steps at the receiver's side of FHSS. Fig. 7(n) indicates that data signal is recovered at the end of the process.

Let  $T_H(t)$  is transmitted signal of FHSS system without interference, while  $T_I(t)$  is interference signal.  $T_I(t)$  is given by:

$$T_I(t) = d'(t)c(t)p'(t) \quad (24)$$

where  $c(t)$  is carrier signal,  $d'(t)$  is interference data signal, and  $p'(t)$  is interference spreading signal.

The interfered data signal of FHSS system is given by:

$$r(t) = T_H(t) + T_I(t) = d(t)c(t)p(t) + d'(t)c(t)p'(t) \quad (25)$$

The received signal at the receiver is the interfered data signal  $r(t)$ . The received signal passes through de-spreading followed by demodulation process. Then, the following signal  $r_m(t)$  is obtained:



$$\begin{aligned}
r_m(t) = & (A^2/4)d(t) + (A^2/4)d(t)\cos(2\pi f_d t) + (A^2/4)d(t)\cos(2\pi t 2h(t)) + \\
& (A^2/8)d(t)\cos(2\pi t 2(h(t) - f_d)) + (A^2/8)d(t)\cos(2\pi t 2(h(t) + f_d)) + \\
& (A^2/4)d'(t)\cos(2\pi t(h'(t) - h(t))) + (A^2/4)d'(t)\cos(2\pi t(h'(t) + h(t))) + \\
& (A^2/8)d'(t)\cos(2\pi t(h'(t) - h(t) - 2f_d)) + (A^2/8)d'(t)\cos(2\pi t(h'(t) - h(t) + 2f_d)) + \\
& (A^2/8)d'(t)\cos(2\pi t(h'(t) + h(t) - 2f_d)) + (A^2/8)d'(t)\cos(2\pi t(h'(t) + h(t) + 2f_d)) \quad (26)
\end{aligned}$$

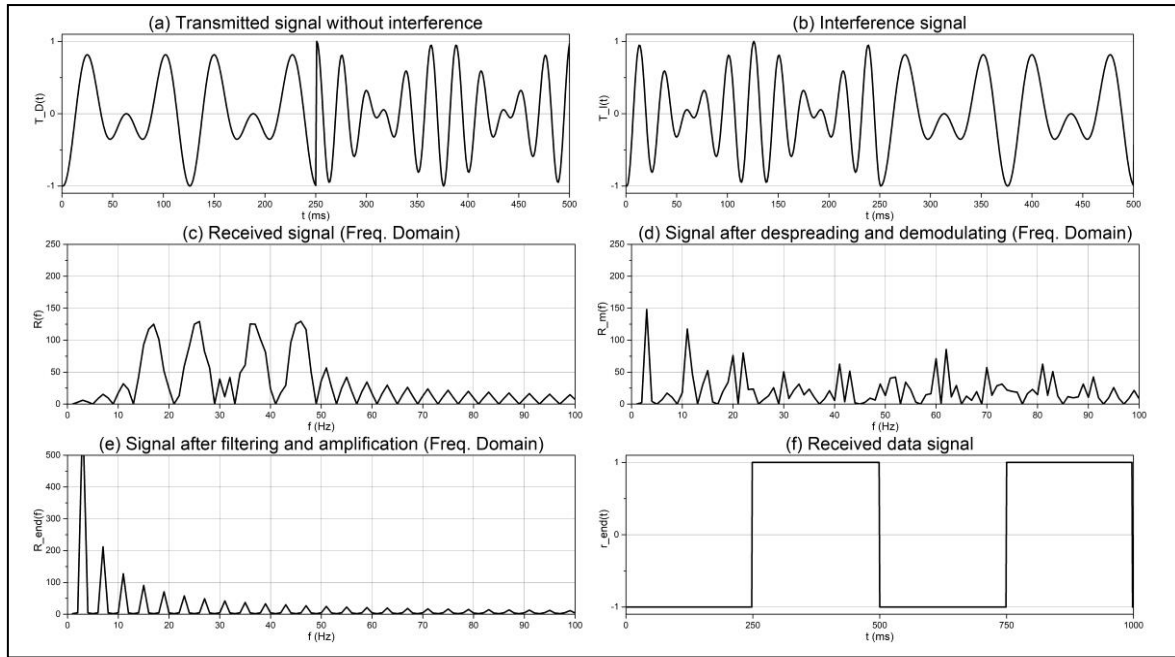


Fig. 7. Signal processing at receiver for FHSS system with hopping frequency 20 and 40 Hz

The signal  $r_m(t)$  after despreading and demodulation processes will be filtered by using FFT low-pass filter  $F(f)$ . Filter  $F(f)$  is similar to the filter used in DSSS system which has filter bandwidth  $f_d$ . Given the conditions that; (a)  $h_i \neq h'_i$ , (b)  $h_i > \frac{3}{2}f_d$ , (c)  $h'_i > \frac{3}{2}f_d$  and (d)  $|h_i - h'_i| > 3f_d$ , then the filtered signal  $r_F(t)$  below is obtained:

$$r_F(t) \approx \left[ \frac{A^2}{4} \left( \sum_{i=-\infty}^{\infty} d_i \psi(t - iT_d) \right) \right] \approx \frac{A^2}{4} d(t) \quad (27)$$

For FHSS system, the filtered signal  $r_F(t)$  with  $A = 1$  will be amplified with gain 4 to recover the data signal  $d(t)$ .

$$r_{end}(t) \approx 4r_F(t) \approx d(t) \quad (28)$$

Like DSSS system, there may be other signal components that can pass through the filtering process, if the following conditions happen:

1. If  $h_i = \frac{3}{2}f_d$ ;  $|h_i - h'_i| > 3f_d$ ;  $h'_i > \frac{9}{2}f_d$ ;  $h'_i \neq h_i$ , then the filtered signal  $r_F(t)$  is

$$r_F(t) \approx \left[ \frac{A^2}{4} d(t) \right] + \left[ \frac{A^2}{8} d(t) \cos(2\pi t f_d) \right] \quad (29)$$

2. If  $h_i = \frac{1}{2}f_d$ ;  $|h_i - h'_i| > 3f_d$ ;  $h'_i > \frac{7}{2}f_d$ ;  $h'_i \neq h_i$ , then the filtered signal  $r_F(t)$  is

$$r_F(t) \approx \left[ \frac{A^2}{4} d(t) \right] + \left[ \frac{3A^2}{8} d(t) \cos(2\pi t f_d) \right] \quad (30)$$

3. If  $h_i' = h_i$ ;  $|h_i - h_i'| = 0$ ;  $h_i > \frac{3}{2}f_d$ ;  $h_i' > \frac{3}{2}f_d$ , then the filtered signal  $r_F(t)$  is

$$r_F(t) \approx \left[ \frac{A^2}{4} d(t) \right] + \left[ \frac{A^2}{4} d'(t) \right] \quad (31)$$

From the mathematical analysis above, it can be concluded that FHSS system is robust against this type of interference if the following conditions are met: 1)  $h_i' \neq h_i$ ; 2)  $h_i > \frac{3}{2}f_d$ ; 3)  $h_i' > \frac{3}{2}f_d$ ; and 4)  $|h_i - h_i'| > 3f_d$ .

As explained before,  $h_i$  is spreading frequency series of the data signal. Here,  $h_i'$  is spreading frequency series of interference. The required conditions  $h_i > \frac{3}{2}f_d$  and  $h_i' > \frac{3}{2}f_d$  match to the trend of the obtained BER data shown in Table 2. If the hopping frequency (spreading frequency series) is greater than 1.5 times of the bitrate, then we get small BER. And, if we keep increasing the spreading frequency series, then BER value gets smaller indicating the system performance becomes more optimal.

When the hopping frequency are varied from a pair of 20 and 40 Hz to 20 and 100 Hz, we can see a significant change in BER value. This can be understood from the fact that condition of  $|h_i - h_i'| > 3f_d$  has been satisfied. Let assess the first case when the hopping frequency are 20 and 40 Hz. The spreading frequency series of the data signal will be  $h_1 = 20$  Hz and  $h_2 = 40$  Hz, while the spreading frequency series of the interference will be in vice versa,  $h_1' = 40$  Hz and  $h_2' = 20$  Hz. Thus, the absolute difference between  $h_i$  and  $h_i'$  will be less than  $3f_d$ , or,  $|h_i - h_i'| < 3f_d$ . Hence, this does not meet condition 4, while conditions 1 to 3 are still met. At these frequency hopping, the resulted BER value is 3.774 %.

Let also assess the second case when the hopping frequency 20 Hz and 100 Hz. The  $h_1$  and  $h_2$  will be 20 and 100 Hz, while  $h_1'$  and  $h_2'$  are 100 and 20 Hz respectively. Thus, the absolute difference between  $h_i$  and  $h_i'$  is larger than  $3f_d$ , or,  $|h_i - h_i'| > 3f_d$ . Hence, all the required conditions (1 to 4) are satisfied which results in very small BER. In this case, the resulted BER value is 0.066 % which is far smaller compared to the first case.

### 3.3. Remarks

After simulation tests and mathematical analysis have been performed, we can notice the ability of each system under wideband interference. We can point out that FHSS has a better performance compared to DSSS. Here, the following important remarks can be proposed;

- (1) DSSS system has two conditions; 1)  $f_s > f_d$ , and 2)  $p_i' \neq p_i$ . The first condition,  $f_s > f_d$ , is general requirement for DSSS system. The second condition,  $p_i' \neq p_i$ , means that the pseudo noise series of the data signal must be different to the pseudo noise series of the interference signal. Where it only happens if:

$$\begin{array}{ll} \text{Suppose:} & p_i = 1, 1, 0, 0, 1, 0, 1, 0 \dots \\ \text{Then:} & p_i' = 0, 0, 1, 1, 0, 1, 0, 1 \dots \end{array}$$

Both  $p_i$  and  $p_i'$  are binary data which are randomly generated by the system. Therefore, there may be one and more similar pseudo noise series between  $p_i$  and  $p_i'$ . Hence, the chance for  $p_i' \neq p_i$  is 50%. This is one of the reasons that makes DSSS is less optimal than FHSS.

- (2) FHSS has four conditions; 1)  $h_i > \frac{3}{2}f_d$ , 2)  $h_i' > \frac{3}{2}f_d$ , 3)  $h_i' \neq h_i$ , and 4)  $|h_i - h_i'| > 3f_d$ . The first and second conditions,  $h_i > \frac{3}{2}f_d$  and  $h_i' > \frac{3}{2}f_d$ , are compulsory requirement in FHSS. These two conditions are like  $f_s > f_d$  in DSSS system. The condition  $h_i' \neq h_i$  is similar to  $p_i' \neq p_i$  in DSSS system. However, the possibility for  $h_i' \neq h_i$  in FHSS is greater than  $p_i' \neq p_i$  in DSSS system. This is due to the spreading frequency series  $h_i$  is a type of positive decimal data ( $h_i > 0$ ), while  $p_i$  is a type of binary data ( $p_i = 0$  or  $1$ ). Moreover, the condition  $|h_i - h_i'| > 3f_d$  has a greater possibility, because if  $h_i \gg f_d$  then the absolute difference between  $h_i$  and  $h_i'$  will also be much greater than  $f_d$ .

#### 4. Conclusion

In this paper, performance evaluation and mathematical analysis of DSSS and FHSS systems subject to wideband interference have been presented. Simulation has been performed to evaluate the performance of both systems when the spreading frequencies are varied. Simulation results demonstrate that BER of both systems are decreased, when spreading frequencies are increased. Mathematical analysis verifies the performance of each system, where the optimum conditions for each system has also been demonstrated. It has been proposed that DSSS requires two conditions, while FHSS requires 4 conditions, to meet its optimum condition against wideband interference. Based on simulation results and mathematical analysis, FHSS is more optimal than DSSS, especially when the system is subject to wideband interference.

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